# 6" Riser Deflection Verification

References	"ACI 318 14" "Notes of ACI 318 08 Building Code Requirements for Structural Concrete"	software
Design File	6" Riser.ebf	
Description	Verification of Eriksson Beam's current deflection calculation and an additional deflection computation following the procedure outlined in Example 10.2 contained with PCA Notes on ACI 318	

**Eriksson** 

# **Section Geometry and Section Properties**

Length	L = 13.75  ft
Width	w = 4 ft
Height	h = 6  in
Moment of Inertia	$I_{xx} = \frac{1}{12} \cdot w \cdot h^3 = 864 \text{ in}^4$
Area	$A_g = w \cdot h = 288 \text{ in}^2$
Reinforcement Information	
Area of Mild Steel	$A_s = 6.0.31 \text{ in}^2 = 1.86 \text{ in}^2$
Depth to Mild Steel	d = 4.4375 in
Material Properties	
Steel Elastic Modulus	$E_{_S} = 29000 \text{ ksi}$
Concrete Weight	$w_c = 150 \frac{lbf}{ft^3}$
Initial Concrete Elastic Modulus	$E_{ci} = 3031.24 \text{ ksi}$
Final Concrete Elastic Modulus	$E_{_C} = 4695.98 \text{ ksi}$
Final Concrete Strength	$f_c = 6 \text{ ksi}$
Modulus of Rupture	$f_r = 7.5 \cdot \sqrt{\frac{f_c}{\text{psi}}}$ psi = 580.9475 psi
Modular Ratio	$\eta = \frac{E_s}{E_c} = 6.1755$
Loading and Demand	
Self Weight	$w_{sw} = A_g \cdot w_c = 300 \frac{\text{lbf}}{\text{ft}}$
Superimposed Dead Load	$w_{sd} = 72 \frac{lbf}{ft^2} \cdot w = 288 \frac{lbf}{ft}$
Live Load	$w_1 = 100 \frac{\text{lbf}}{\text{ft}^2} \cdot w = 400 \frac{\text{lbf}}{\text{ft}}$

Total Dead Load

Total Loading

Dead Load Moment

Live Load Moment

Total Moment

# **Cracked Section Properties**

$$\rho = \frac{A_s}{w \cdot d} = 0.0087$$

$$k = \sqrt{2 \cdot \rho \cdot \eta + (\rho \cdot \eta)^2} - \rho \cdot \eta = 0.2789$$

$$c = k \cdot d = 1.2375 \text{ in}$$

$$I_{cr} = w \cdot c \cdot (0.5 \cdot c)^2 + \frac{w \cdot c^3}{12} + \eta \cdot A_s \cdot (d - c)^2 = 147.9428 \text{ in}^4$$

## **Effective Moment of Inertia**

Cracking Moment

$$M_{cr} = \frac{f_r \cdot I_{xx}}{0.5 \cdot h} = 13.9427 \text{ kip ft}$$

Effective Moment of Inertia from dead load

$$I_{e.d} = \min\left[\left[I_{xx}\left(\left(\frac{M_{cr}}{M_{d}}\right)^{3} \cdot I_{xx} + \left(1 - \left(\frac{M_{cr}}{M_{d}}\right)^{3}\right) \cdot I_{cr}\right)\right]\right] = 864 \text{ in }^{4}$$

 $\lambda_{\Delta} = 2$ 

Effective Moment of inertia from all loads

$$I_{e.t} = \left(\frac{M_{cr}}{M_t}\right)^3 \cdot I_{xx} + \left(1 - \left(\frac{M_{cr}}{M_t}\right)^3\right) \cdot I_{cr} = 300.4095 \text{ in}^4$$

Additional Deflection Multiplier

$$\begin{split} & w_d = w_{sw} + w_{sd} = 0.588 \, \frac{\text{kip}}{\text{ft}} \\ & w_t = w_d + w_l = 0.988 \, \frac{\text{kip}}{\text{ft}} \\ & M_d = \frac{w_d \cdot L^2}{8} = 13.8961 \, \text{kip ft} \\ & M_l = \frac{w_l \cdot L^2}{8} = 9.4531 \, \text{kip ft} \end{split}$$

$$M_t = M_d + M_1 = 23.3492 \text{ kip ft}$$

#### Deflections based on example 10.2 from PCA Notes

The main changes here are that it appears additional deflections due to creep and shrinkage are only based on the elastic response (similiar to how was are handling prestressed beams). So this term is computed seperately. Because of this, the deflection due to creep is isolated as it's own term.

Deflection due to self weight

Deflection due to super-imposed dead load

$$\Delta_{sw} = \frac{5 \cdot w_{sw} \cdot L^{-1}}{384 \cdot E_{ci} \cdot I_{e.d}} = 0.0921 \text{ in}$$

л

$$\Delta_{sd} = \frac{5 \cdot w_{sd} \cdot L}{384 \cdot E_c \cdot I_{e,d}} = 0.0571 \text{ in}$$

 $\Delta_d = \Delta_{sw} + \Delta_{sd} = 0.1492 \text{ in}$ 

Deflection due to all dead load

Deflection due to all loading

$$\Delta_t = \frac{5 \cdot w_{_{SW}} \cdot L^4}{384 \cdot E_{_{Ci}} \cdot I_{_{e,t}}} + \frac{5 \cdot \left(w_t - w_{_{SW}}\right) \cdot L^4}{384 \cdot E_c \cdot I_{_{e,t}}} = 0.6572 \text{ in}$$

 $\Delta_{final} = \left(\lambda_{\Delta} + 1\right) \cdot \Delta_{d} + \Delta_{l} = 0.9556 \text{ in}$ 

Deflection due to live load

 $\Delta_1 = \Delta_t - \Delta_d = 0.508 \text{ in}$ 

The deflection due to live load is computed indirectly. Here we are quantifying it as the total deflection minus the deflection due to dead load. It is defined this way because the increase in live load causes more deflection because the change to the moment of inertia.

Total long term deflection with creep

Alternatively, the equation can be rearranged to the following

Additional Deflection due to creep

Total long term deflection with creep

#### Composite deflections based on example 10.2 from PCA Notes

#### Toppin Geometry

Topping Thickness

Moment of Inertia

Area

#### **Material Properties**

Concrete Weight

Topping Concrete Elastic Modulus Topping Concrete Strength

$$t = 2 \text{ in}$$

$$I_{xx.t} = \frac{1}{12} \cdot w \cdot t^{3} = 32 \text{ in}^{4}$$

$$A_{t} = w \cdot t = 96 \text{ in}^{2}$$

 $\Delta_{cr} = \lambda_{\Lambda} \cdot \Delta_{d} = 0.2984$  in

 $\Delta_{final} = \Delta_{cr} + \Delta_t = 0.9556$  in

 $w_c = 150 \frac{1bf}{ft^3}$  $E_{ct} = 3834.25 \text{ ksi}$  $f_{ct} = 6 \text{ ksi}$ 

**Topping Modular Ratio** 

$$\eta_t = \frac{E_{ct}}{E_c} = 0.8165$$

# **Composite Section Properties**

Composite Area

Composite Centroid

$$A_{c} = A_{q} + \eta_{t} \cdot A_{t} = 366.3836 \text{ in}^{2}$$

$$c_{yc} = \frac{\frac{h}{2} \cdot A_g + \left(h + \frac{t}{2}\right) \cdot A_t \cdot \eta_t}{A_c} = 3.8558 \text{ in}$$

Composite Moment of Inertia

$$I_{xx.c} = I_{xx} + I_{xx.t} + A_g \cdot \left(\frac{h}{2} - c_{yc}\right)^2 + \eta_t \cdot A_t \cdot \left(h + \frac{t}{2} - c_{yc}\right)^2$$
$$I_{xx.c} = 1881.8295 \text{ in}^4$$

 $w_{dc} = 72 \frac{\text{lbf}}{\text{ft}^2} \cdot w = 288 \frac{\text{lbf}}{\text{ft}}$ 

 $w_{d} = w_{sw} + w_{sd} = 0.588 \frac{\text{kip}}{\text{ft}}$ 

 $w_{sus} = w_d + w_{dc} = 0.876 \frac{\text{kip}}{\text{ft}}$ 

 $w_t = w_{sus} + w_1 = 1.276 \frac{\text{kip}}{\text{ft}}$ 

#### Additional Loading

- Composite Dead Load
- Total Non-Composite Loading
- Total Sustained Loading
- **Total Loading**
- Sustained Moment

 $M_{sus} = \frac{w_{sus} \cdot L^2}{8} = 20.7023 \text{ kip ft}$ 

 $M_t = \frac{w_t \cdot L^2}{8} = 30.16 \text{ kip ft}$ 

# Total Moment

#### **Effective Moment of Inertia**

Non-Composite Cracking Moment 
$$M_{cr} = \frac{f_r \cdot I_{xx}}{0.5 \cdot h} = 13.94 \text{ kip ft}$$

**Composite Cracking Moment** 

$$M_{cr.c} = \frac{I_{xx.c}}{c_{yc}} \cdot f_r - M_d \cdot \left(\frac{\left(\frac{I_{xx.c}}{c_{yc}}\right)}{\left(\frac{I_{xx}}{0.5 \cdot h}\right)} - 1\right) = 13.98 \text{ kip ft}$$

Composite Cracked Moment of Inertia

(From software)

$$I_{cr.c} = 324 \text{ in}^4$$

Sustained Effective Moment of Inertia

$$I_{e.sus} = \min\left[\left[I_{xx.c}\left(\left(\frac{M_{cr.c}}{M_{sus}}\right)^{3} \cdot I_{xx.c} + \left(1 - \left(\frac{M_{cr.c}}{M_{sus}}\right)^{3}\right) \cdot I_{cr.c}\right)\right]\right] = 803.2 \text{ in}^{4}$$

Non-Composite Effective Moment of inertia

$$I_{e.nc.t} = \min\left[\left[I_{xx}\left(\left(\frac{M_{cr}}{M_{d}}\right)^{3} \cdot I_{xx} + \left(1 - \left(\frac{M_{cr}}{M_{d}}\right)^{3}\right) \cdot I_{cr}\right)\right]\right] = 864 \text{ in }^{4}$$

Composite Effective Moment of inertia

$$I_{e.c.t} = \left(\frac{M_{cr.c}}{M_t}\right)^3 \cdot I_{xx.c} + \left(1 - \left(\frac{M_{cr.c}}{M_t}\right)^3\right) \cdot I_{cr.c} = 479.1 \text{ in}^4$$

# Deflections

Deflection due to self weight, creep

Deflection due to self weight, instantaneous

$$\Delta_{sw.cr} = \frac{5 \cdot w_{sw} \cdot L^4}{384 \cdot E_{ci} \cdot I_{e.sus}} = 0.0991 \text{ in}$$

$$\boldsymbol{\Delta}_{sw.i} = \frac{5 \cdot w_{sw} \cdot \boldsymbol{L}^{4}}{384 \cdot \boldsymbol{E}_{ci} \cdot \boldsymbol{I}_{e.nc.t}} = 0.0921 \text{ in}$$

Deflection due to non-composite dead load, creep

$$\Delta_{sd.cr} = \frac{5 \cdot w_{sd} \cdot L^4}{384 \cdot E_c \cdot I_{e.sus}} = 0.0614 \text{ in}$$

Deflection due to non-composite dead load, instantaneous

$$\Delta_{sd.i} = \frac{5 \cdot w_{sd} \cdot L^{4}}{384 \cdot E_{c} \cdot I_{e.nc.t}} = 0.057 \text{ in}$$

Deflection due to composite dead load, creep

$$\Delta_{dc.cr} = \frac{5 \cdot w_{dc} \cdot L^4}{384 \cdot E_c \cdot I_{e.sus}} = 0.061 \text{ in}$$

Deflection due to composite dead load, instantaneous

$$\Delta_{dc.i} = \frac{5 \cdot w_{dc} \cdot L^4}{384 \cdot E_c \cdot I_{e.c.t}} = 0.103 \text{ in}$$

Deflection due to live load, instantaneous

$$\begin{split} \Delta_{1.i} &= \frac{5 \cdot w_1 \cdot L}{384 \cdot E_c \cdot I_{e.c.t}} = 0.143 \text{ in} \\ \Delta_{t.cr} &= \Delta_{sw.cr} + \Delta_{sd.cr} + \Delta_{dc.cr} = 0.222 \text{ in} \end{split}$$

 $\boldsymbol{\Delta}_{cr} = \boldsymbol{\Delta}_{t.\,cr} \cdot \boldsymbol{\lambda}_{\boldsymbol{\Delta}} = \texttt{0.444 in}$ 

 $\Delta_{final} = \Delta_{cr} + \Delta_{t,i} = 0.839 \text{ in}$ 

 $\label{eq:lass_swith} \boldsymbol{\Delta}_{t.i} = \boldsymbol{\Delta}_{sw.i} + \boldsymbol{\Delta}_{sd.i} + \boldsymbol{\Delta}_{dc.i} + \boldsymbol{\Delta}_{l.i} = 0.395 \; \text{in}$ 

Total deflections, instantaneous

Total deflections, creep

Total additional deflections

Total long term deflection with creep

# Total Deflections due to Load Cases

Total Self Weight

Total Non-Composite Dead Load

Total Composite Dead Load

Total Live Load

$\boldsymbol{\Delta}_{sw} = \boldsymbol{\Delta}_{sw.i} + \boldsymbol{\lambda}_{\boldsymbol{\Delta}} \cdot \boldsymbol{\Delta}_{sw.cr} = 0.29 \text{ in}$
$\boldsymbol{\Delta}_{sd} = \boldsymbol{\Delta}_{sd.i} + \boldsymbol{\lambda}_{\Delta} \cdot \boldsymbol{\Delta}_{sd.cr} = 0.18 \text{ in}$
$\boldsymbol{\Delta}_{dc} = \boldsymbol{\Delta}_{dc.i} + \boldsymbol{\lambda}_{\Delta} \cdot \boldsymbol{\Delta}_{dc.cr} = 0.226 \text{ in}$
$\Delta_{l} = \Delta_{l.i} = 0.143 \text{ in}$